IESTI05 – Edge Al

Machine Learning
System Engineering

2. Introduction to Embedded Linux and Raspberry Pi Setup







Embedded Linux

The Operating System (OS)

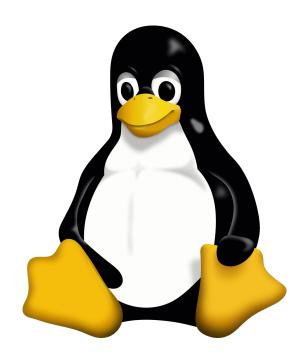
An operating system (OS) is essential software that manages computer hardware and software resources, providing standard services for computer programs. It is the core software that runs on a computer, serving as an intermediary between hardware and application software. The OS oversees the computer's memory, processes, device drivers, files, and security protocols.

1. Key functions:

- Process management: Allocating CPU time to different programs
- Memory management: Allocating and freeing up memory as needed
- File system management: Organizing and keeping track of files and directories
- Device management: Communicating with connected hardware devices
- User interface: Providing a way for users to interact with the computer

2. Components:

- Kernel: The core of the OS that manages hardware resources (i.e., Linux)
- Shell: The user interface for interacting with the OS
- File system: Organizes and manages data storage
- Device drivers: Software that allows the OS to communicate with hardware



What is Embedded Linux?

- A lightweight Linux-based OS for embedded systems
- Customizable, open-source, and widely adopted
- Used in routers, drones, SBCs, industrial systems

Raspberry Pi OS Lite (64-bit) is a minimal, headless <u>Linux distribution</u> for the Raspberry Pi. It is <u>based on Debian</u> (like the desktop version), but it <u>excludes a graphical desktop environment</u> and most bundled applications, providing just the core operating system and essential command-line tools

Why Use Linux in Embedded Systems?

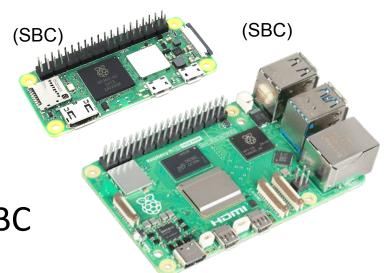
- Open-source and free
- Highly flexible and customizable
- Large developer ecosystem
- Reliable and proven in production

Characteristics

UI: Usually headless

Size: Minimal

Hardware: Targeted SBC



(Compute Module / SoM)



(Compute Module / SoM)



Linux System Components

- Firmware/ROM
- Bootloader e.g., U-Boot
- Device tree hardware description
- Kernel core OS functions
- Root filesystem user space tools
- Init system systemd or BusyBox
- Applications

Embedded Linux Boot Process Layers

Applications
User programs and services running in user space

Init System
Starts user space, services, and background processes (systemd, BusyBox init)

Root Filesystem
User space tools, libraries, configurations

Kernel
Core OS functions: scheduling, memory, device drivers

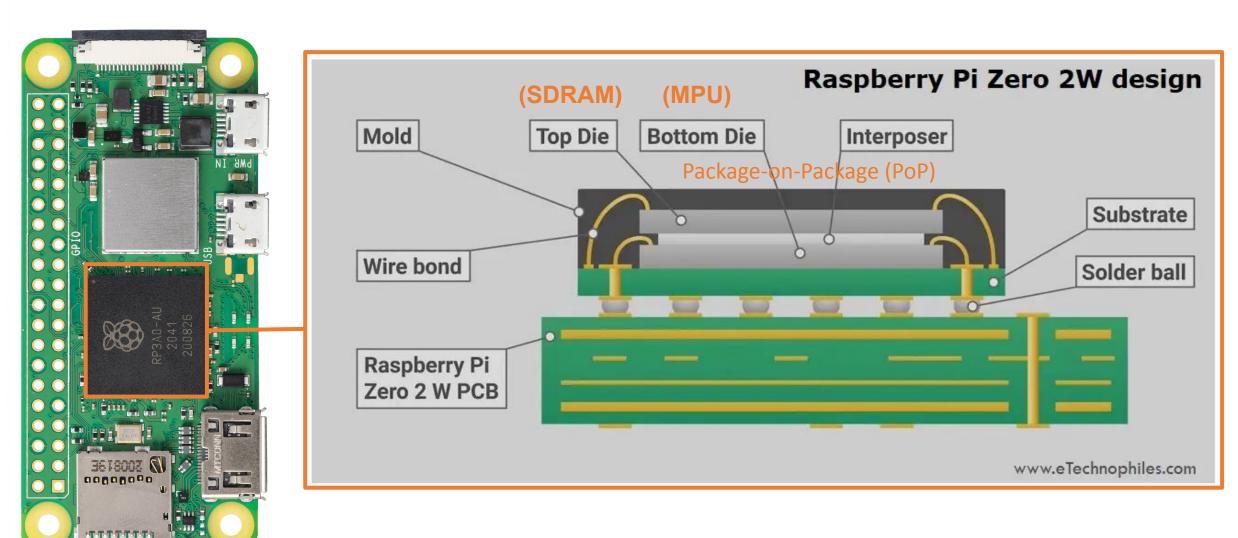
Device Tree Describes hardware layout to the kernel

Bootloader Initial hardware setup, loads kernel (e.g., U-Boot)

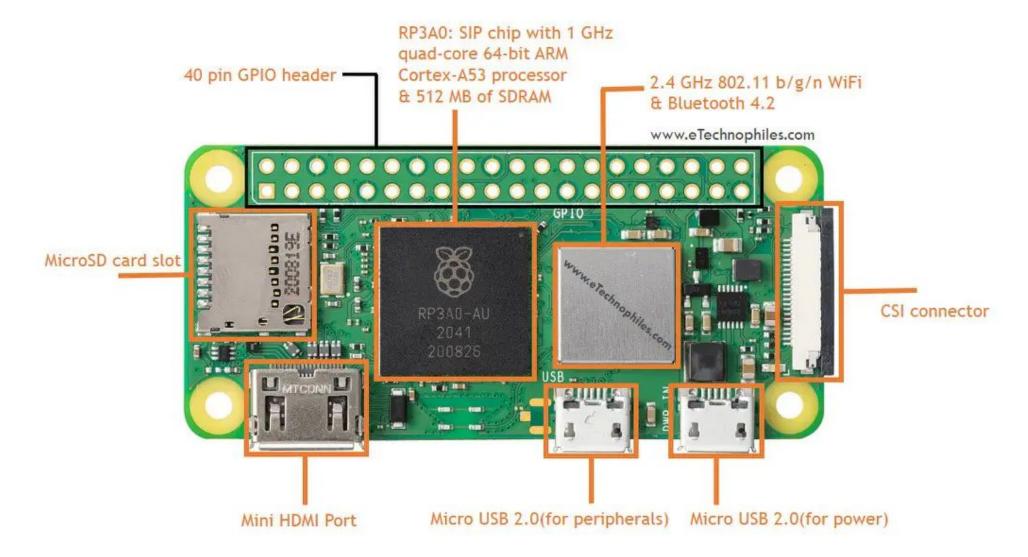
Firmware/ROM Very first code (e.g., CPU internal boot ROM)

Raspberry Pi 2W

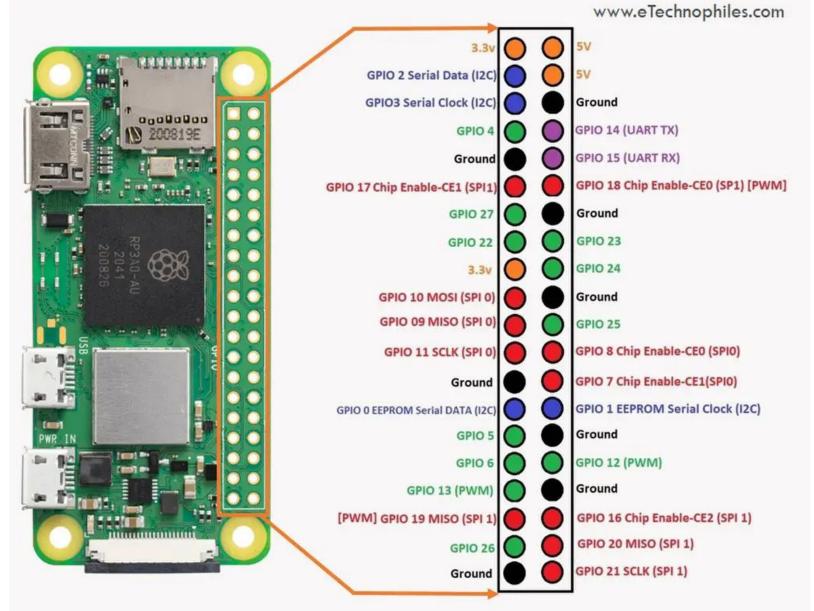
Broadcom BCM2710A1 SoC (System-on-a-chip)



Board Layout



GPIO pinout



Installing the OS

Use Raspberry Pi Imager https://www.raspberrypi.com/software/

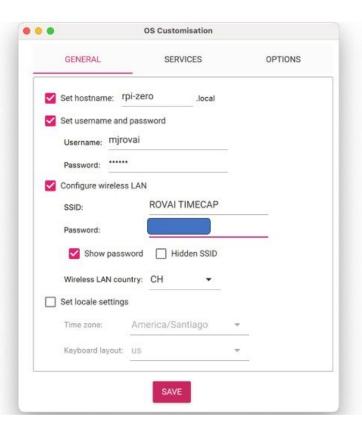
and select:

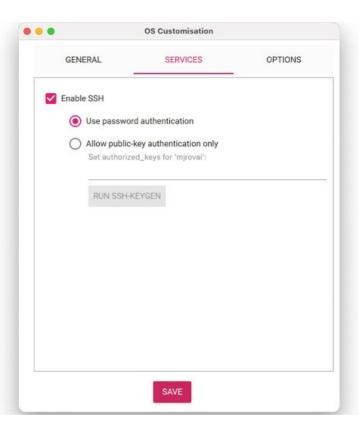
- RASPBERRY PI ZERO 2W
- RASPBERRY PI OS LITE (64-BIT)



Headless setup: enable SSH, Wi-Fi config

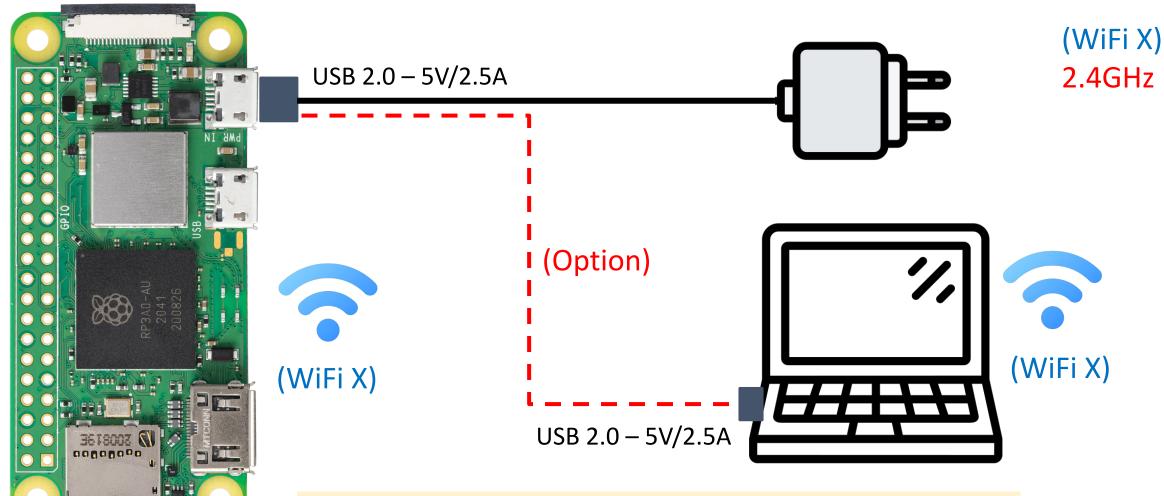
Define hostname, username, and password





Power Supply and WiFi Network





Rasp Pi Zero and Notebook should be on the same WiFi network

Connecting to the Pi – SSH Via Terminal

- Enter with: ssh username@hostname.local (i.e., mjrovai@raspi-zero.local)
 - Once in the Raspi-Zero, use hostname —I to get the IP Address

```
marcelo_rovai — mjrovai@raspi-zero: ~ — ssh mjrovai@raspi-zero.local — 96×16

(base) marcelo_rovai@Marcelos-MacBook-Pro ~ % ssh mjrovai@raspi-zero.local

mjrovai@raspi-zero.local's password:

Linux raspi-zero 6.6.47+rpt-rpi-v8 #1 SMP PREEMPT Debian 1:6.6.47-1+rpt1 (2024-09-02) aarch64

The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/copyright.

Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.
Last login: Sat Aug 9 21:17:39 2025 from 192.168.5.23

mjrovai@raspi-zero: % hostname -I
192.168.4.210 fde3:6154:baa3:1:6e3a:38a:a96a:d8d
mjrovai@raspi-zero: 8
```

Knowing the IP address: Enter with:

Note: On Windows, use Command Prompt (cmd) or PowerShell.

ssh username@ip_address (i.e., mjrovai@ 192.168.4.210)

Initial Linux Commands

- 1. Package mgmt:
 - sudo apt update && upgrade
 - sudo reboot
- 2. System: (Open in a new terminal window)
 - htop

```
. .
               marcelo_rovai — mjrovai@raspi-zero: ~ — ssh mjrovai@raspi-zero.local — 101×22
                                           0.0% Tasks: 23, 7 thr. 119 kehr; 1 running
                                           [ 74] Load average: 0.00 0.08 0.07
                                           0 01 Uptime: 00:09:14
  Swp[
   Main
   674 mjrovai
                  20 0 7556 3172 2404 R 1.3 0.7 0:01.27 http
   661 mjrovai
                                               0.7 1.5 0:00.32 sshd: mjrovai@pts/0
                                                   2.6 0:03.58 /sbin/init
                       164M 11300 8344
                                                   1.6 0:00.40 /lib/systemd/systemd-journald
    230
                                     6112
                                                   1.6 0:00.47 /lib/systemd/systemd-udevd
                         26552 6676 4372
                                                   1.6 0:00.33 /lib/systemd/systemd-timesyncd
                        90712 6888
                                     5992
                        90712 6888 5992
                                                   1.6 0:00.00 /lib/systemd/systemd-timesyncd
                                                   0.7 0:00.54 avahi-daemon: running [raspi-zero.
                                     2812
                          6696 2200 2072
                                                   0.5 0:00.01 /usr/sbin/cron -f
                                                   0.9 0:00.71 /usr/bin/dbus-daemon --system --ad
                                3952 3312
                                                   1.6 0:00.07 /usr/lib/polkit-1/polkitd --no-deb
                           229M 6720 5952
F1Help F2Setup F3SearchF4FilterF5Tree F6SortByF7Nice -F8Nice +F9Kill F10Quit
```

Increasing SWAP Memory

- First, turn off the swap-file:
 sudo dphys-swapfile swapoff
- Next, open and modify the file /etc/dphys-swapfile. For that, we will use the nano text editor:
 - sudo nano /etc/dphys-swapfile
 - a. Search for the CONF_SWAPSIZE variable (default is 200) and
 - b. update it to 2000: CONF_SWAPSIZE=2000, and
 - c. save the file: $CTRL+X \rightarrow Y => Enter$.
- 3. Next, turn on the swapfile again and reboot the Raspberry Pi:
 - sudo dphys-swapfile setupsudo dphys-swapfile swapon
 - sudo reboot

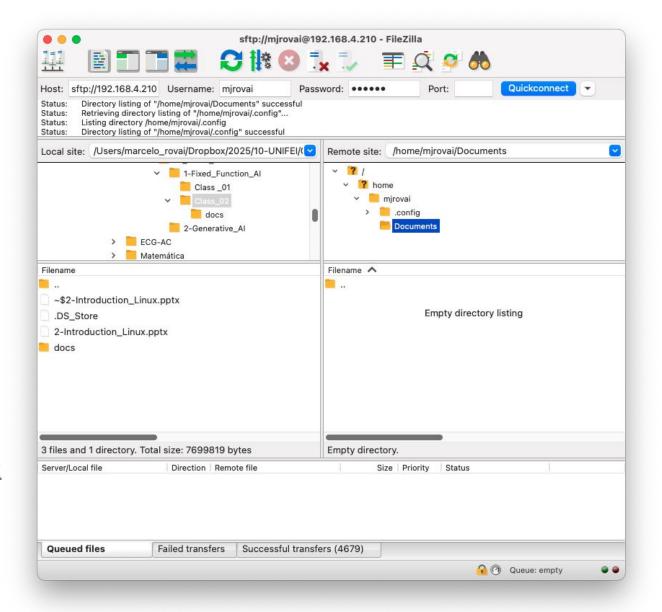
Linux: Basic Commands

- clear -> Clear the terminal
- pwd -> Show the current directory: /home/mjrovai
- Is -> Lists the current directory content: (empty)
- Mkdir <name> -> Creates a directory: mkdir Documents
- cd <dir> -> Change to a directory cd Documents

```
mirovai@raspi-zero: - // Documents - ssh mirovai@192.168.4....
mirovai@raspi-zero: - $ pwd
/home/mirovai
mirovai@raspi-zero: - $ ls
mirovai@raspi-zero: - $ mkdir Documents
mirovai@raspi-zero: - $ ls
Documents
mirovai@raspi-zero: - $ cd Documents
mirovai@raspi-zero: - $ cd Documents
mirovai@raspi-zero: - $ cd Documents
```

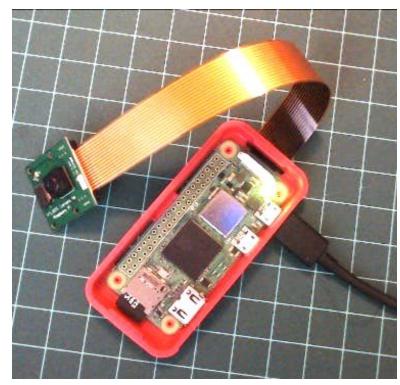
Transferring files using FTP

- Install FileZila Client in the Desktop https://filezilla-project.org/download.php?type=client
- 2. Enter with Host Credentials (i.e., sftp://192.168.4.210)



Using the Camara Module

- Install camera software (if not pre-installed): sudo apt-get install libcamera-apps
- 2. List the installed cameras: rpicam-hello --list-cameras
- 3. Capture a 640x480 JPEG image: rpicam-jpeg --output test_cli_camera.jpg --width 640 --height 480
- 4. Use the command Is to check if the image was saved in the current directory and transfer it to your desktop with FileZilla.



Tips

- Connecting the Raspberry Pi to the Computer via USB can be unstable for heavy use. Prefer a 5V/2.5 Power Supply (same as used for mobile phones)
- The WiFi Network should be 2.4GHz
- Always turn off the Raspberry Pi, using the command: sudo shutdown -h now
- Install packages using sudo apt install <package name>

Questions?

Prof. Marcelo J. Rovai

rovai@unifei.edu.br

